## How to launch our ROS code on the robot:

### Run Roscore on the desktop (during testing)

* Run “roscore” on desktop

### Launch the ROS stuff on the RaspberryPi

* SSH into the Pi
* Run “roslaunch slash\_dash\_bang\_hash slash\_dash\_bang\_hash.launch”

### Launch Vision node

* Open a new terminal
* Run “roslaunch slash\_dash\_bang\_hash vision.launch”

### Launch Referee

* Open a new terminal
* Run “roslaunch soccerref referee.launch”